



- q Routing algorithms
- q ARPAnet routing



Rooting or Routing

- q *Rooting* is what fans do at football games, what pics do for truffles under oak trees in the Vaucluse, and what nursery workers intent on propagation do to cuttings from plants.
- *Routing* is how one creates a beveled edge on a table top or sends a corps of infanctrymen into full scale, disorganized retreat

Ref: Piscitello and Chapin, p413

Routeing or Routing

- q Routeing: British
- q Routing: American
- q Since Oxford English Dictionary is much heavier than any other dictionary of American English, British English generally prevalis in the documents produced by ISO and CCITT; wherefore, most of the international standards for routing standards use the routeing spelling.

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Routing Techniques Elements

- Performance criterion: *Hops*, Distance, *Speed*,
 Delay, Cost
- q Decision time: Packet, session
- q Decision place: Distributed, centralized, Source
- q Network information source: None, local, adjacent nodes, nodes along route, all nodes
- **q** Routing strategy: Fixed, *adaptive*, random, flooding
- q Adaptive routing update time: Continuous, *periodic*, topology change, major load change

Distance Vector vs Link State

- **q Distance Vector**: Each router sends a vector of distances to its neighbors. The vector contains distances to all nodes in the network.
 Older method. Count to infinity problem.
- **q** Link State: Each router sends a vector of distances to all nodes. The vector contains only distances to neighbors. Newer method. Used currently in internet.

Dijkstra's Algorithm

- q Goal: Find the least cost paths from a given node to all other nodes in the network
- **q** Notation:
 - d_{ij} = Link cost from i to j if i and j are connected
 - $\vec{D_n}$ = Total path cost from s to n
 - M = Set of nodes so far for which the least cost path is known
- q Method:
 - q Initialize: $M = \{s\}, D_n = d_{sn}$
 - q Find node w \notin M, whose Dn is minimum



Example (Cont)

	Μ	D2	Path	D3	Path	D4	Path	D5	Path	D6	Path
1	{1}	2	1-2	5	1-3	1	1-4	∞	-	∞	_
2	{1,4}	2	1-2	4	1-4-3	1	1-4	2	1-4-5	∞	-
3	${1,2,4}$	2	1-2	4	1-4-3	1	1-4	2	1-4-5	∞	-
4	{1,2,4,5}	2	1-2	3	1-4-5-3	1	1-4	2	1-4-5	4	1-4-5-6
5	{1,2,3,4,5}	2	1-2	3	1-4-5-3	1	1-4	2	1-4-5	4	1-4-5-6
6	{1,2,3,4,5,6	}2	1-2	3	1-4-5-3	1	1-4	2	1-4-5	4	1-4-5-6

Dijkstra's Routing Algorithm

q Apply to the following network and compute paths from node 1.



	М	D2	Path	D3	Path	D4	Path	D5	Path	D6	Path
1											
2											
3											
4											
5											
6											

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Dijkstra's routing algorithm

q Apply to the following network and compute paths from node 1.



	М	D2	Path	D3	Path	D4	Path	D5	Path	D6	Path
1	{1}	1	1-2	∞	-	4	1-4	∞	-	∞	-
2	{1,2}	1	1-2	4	1-2-3	4	1-4				
3	{1,2,3}	1	1-2	4	1-2-3	4	1-4	2	1-2-5	6	1-2-3-6
4	{1,2,3,5}	1	1-2	4	1-2-3	3	1-2-5-1	2	1-2-5	6	1-2-3-6
5	{1,2,3,4,5}	1	1-2	4	1-2-3	3	1-2-5-1	2	1-2-5	6	1-2-3-6
6	{1,2,3,4,5,6}	1	1-2	4	1-2-3	3	1-2-5-1	2	1-2-5	6	1-2-3-6

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Bellman-Ford Algorithm

- **q** Notation:
 - h = Number of hops being considered $D^{(h)}_{n}$ = Cost of h-hop path from s to n
- q Method: Find all nodes 1 hop awayFind all nodes 2 hops awayFind all nodes 3 hops away

q Initialize: $D^{(h)}_{n} = \infty$ for all $n \neq s$; $D^{(h)}_{n} = 0$ for all h

q Find jth node for which h+1 hops cost is minimum $D^{(h+1)}_{n} = min_j [D^{(h)}_{j} + D_{jn}]$

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Example (Cont)

h	D (h ₂)	Path	D (h ₃)	Path	D(h	4) Path	D(h ₅)Path	D (h ₆)	Path	
0	8	_	∞	-	8	-	8	_	∞	-	
1	2	1-2	5	1-3	1	1-4	∞	-	∞	-	
2	2	1-2	4	1-4-3	1	1-4	2	1-4-5	10	1-3-6	
3	2	1-2	3	1-5-4-3	1	1-4	2	1-4-5	4	1-4-5-6	
4	2	1-2	3	1-5-4-3	1	1-4	2	1-4-5	4	1-4-5-6	
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5-19

ARPAnet Routing (1969-78)

- q Features: Cost=Queue length,
- q Each node sends a vector of costs (to all nodes) to neighbors. Distance vector
- q Each node computes new cost vectors based on the new info using Bellman-Ford algorithm

ARPAnet Routing Algorithm

	Desti- nation	Delay	Next / node)							Desti- nation	Delay	Next / node	9
	1	0	Ñ		2		3		1		1	0	Ñ	
	2	2	2		0		3		2		2	2	2	
	3	5	3		3		0		2		3	3	4	
	4	1	4		2		2		0		4	1	4	
	5	6	3		3		1		1		5	2	4	
	6	8	3		5		3		3		6	4	4	
	D^1 S^1					,	 D ³	, .	 D4			1 1,2	=	2
												1 1,3	=	5
												1 1,4	=	1
	(a) N ro be	lode 1 outing f efore u	ås table ipdate		(b) Delay vectors sent t neighbor nodes						(c) No afte c	de 1ås er upda	s routin ate and	g table I link
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ARPAnet Routing (1979-86)

- q Problem with earlier algorithm: Thrashing (packets went to areas of low queue length rather than the destination), Speed not considered
- q Solution: Cost=Measured delay over 10 seconds
- q Each node f<u>loods</u> a vector of cost to neighbors.
 Link-state. Converges faster after topology changes.
- q Each node computes new cost vectors based on the new info using Dijkstra's algorithm

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Fig 9.10

ARPAnet Routing (1987+)

q Problem with 2nd Method: Correlation between delays reported and those experienced later : High in light loads, low during heavy loads
 ⇒ Oscillations under heavy loads
 ⇒ Unused capacity at some links, over-utilization of others, More variance in delay more frequent updates

More overhead

Fig 9.11 The Ohio State University

Routing Algorithm





- q Connection-oriented and Connectionless
- q Routing: Least-cost, Flooding, Adaptive
- q Dijkstra's and Bellman-Ford algorithms
- q ARPAnet

Homework

- q Excercise 9.4 (in b assume a unidirectional single loop), 9.10, 9.15
- q Due: Next class