						Timeline							
Task:	Subtasks:	2/15/2016	2/22/2016	2/29/2016	3/7/2016	3/14/2016 3/21/2016	3/28/2016	4/4/2016	4/11/2016	4/18/2016	4/25/2016	5/2/2016	5/9/2016
Project proposal	Overview, design, challenges, methodology, objectives												
	Budget												
	Timeline												
	Gantt												
Design hardware	Edit CAD drawing for robot chassis												
	Design battery circuit												
	Design servo/motor circuit Design mapping												
	circuit												
Order parts													
Print chassis	Legs												
Test electronics	Platform												
	Battery												
	Motors/servos												
	Microcrontroller												
	Wireless				_								
Build hardware	Chassis												
	Battery circuit												
	Motors/servo circuit												
	Environment sensor circuit												
	Rangefinder circuit												
	Wireless communication circuit												
Coding	Communication												
	Locomotion												
	Environment sensor interpretation												
	Motion planning												
	Interfacing												
Testing	Wireless communication												
	Environment sensor data												
	Locomotion												
	Motion planning												
Demo													