Lecture 3: Priority Queues, and a Tree Grows in 247

These slides include material originally prepared by Dr.Ron Cytron, Dr. Jeremy Buhler, and Dr. Steve Cole.

Announcements

- Lab 1 due Friday 2/8 at 11:59 PM
 - Turn in via Gradescope
 - Math hint:

 $a^{\log_b n} = n^{\log_b a}$

- Lab 3 out this Wednesday
 - Has three parts: pre-lab (due 2/12), coding, and write-up parts (due 2/15)

Overview

- What is a Priority Queue
 - ADT
 - Applications
- Some not so great implementations (which you'll explore in Studio 3)
 - Lists
 - Arrays

Overview

- What is a Priority Queue
 - ADT
 - Applications
- Some not so great implementations (which you'll explore in Studio 3)
 - Lists
 - Arrays
- Trees
- Priority Queue using trees
- Using arrays to simulate trees
 - Implementation of this is Lab 3

ADTs from Last Time

- The data structures we reviewed last time (queues, stacks) track the positions of their elements.
 - "Add to the tail"/ "Remove from the head" [queues]
 - "Add to the top"/ "Remove from the top" [stacks]
- Elements themselves were completely generic we neither knew nor cared about their properties.

Working With Ordered Data

- But let's suppose we have data that is *ordered* (e.g. integers).
- Given a collection of such data, we may want to ask questions that depend on the order of the elements.

Working With Ordered Data

- But let's suppose we have data that is *ordered* (e.g. integers).
- Given a collection of such data, we may want to ask questions that depend on the order of the elements.
- **Challenge:** can we efficiently answer these questions when the collection is changing dynamically?

- Garage receives a stream of cars needing repairs.
- Each repair job comes with a deadline.
- Cars may not show up in order of deadlines.

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• Garage receives a stream of cars needing repairs.

• Each repair job comes with a deadline.





1:00 PM

• Garage receives a stream of cars needing repairs.

• Each repair job comes with a deadline.







11:00 AM!!! 11

1:00 PM

5:00 PM

What Do We Want?

- Query: at any time, which car needs to be ready first? (earliest deadline)
- Insertion: new cars can show up at any time, with any deadline.
- Update: when we repair the car with the earliest deadline, which car has next earliest deadline?

More Abstractly...

- Maintain a collection of ordered values [e.g. deadlines]
- Values can be inserted in any order
- At any time, may remove smallest value
- Want to maintain O(1) query time for smallest value

More Abstractly...

- Maintain a "min-first priority queue" PQ
- PQ.insert(v) insert element v

- PQ.extractMin() extract and return minimum element
- PQ.peekMin() must be constant-time

A Few More Details

• PQ has a fixed maximum size [e.g. size of garage]

An item's value *might decrease* while it is in PQ
[e.g. a customer now wants their car back sooner]

Assumptions:

- 1. Items are not known until they are inserted
- 2. An item's value *cannot increase* while it is in PQ

What PQ Methods Might Look Like in Java

- instantiation: PriorityQueue<T>(int size)
 - The queue has a bounded size that is specified upon creation
- insertion into the PQ: Decreaser<T> insert(T thing)
 - The returned "Decreaser" object is often called a handle
 - **Decreaser<T>** allows outside activity to decrease the value of inserted thing
- is the PQ empty? **boolean** isEmpty()
- remove and return the currently smallest **T**: **extractMin()**
- inspect but do not remove the currently smallest T: peekMin()

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We could just as well define a max-first PQ that maintains the largest element. The book makes this choice.

Further Notes on Java Impl (See Lab 3)

• What about Decreaser<T>?

- **T** getValue() to get at the current value of this thing
- void decrease(T newvalue)
- We require that **newvalue** be no greater than the current value for the affected item
- Why is this an operation on an object (Decreaser) outside of the PQ, instead of, say, PQ.decreaseItem(T which, T newvalue)?

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• What about **Decreaser<T>**?

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- Why is this an operation on an object (Decreaser) outside of the PQ, instead of, say, PQ.decreaseItem(T which, T newvalue)?

In the alternative, how long could it take to locate "which"? Is the entry "which" unique?



new PriorityQueue(5)





new PriorityQueue(5)

- Can hold up to 5 elements
- Is initially empty





















We decrease 247 using its *handle*, the Decreaser object, which has a direct reference to the 247 entry.

Why do we need the Decreaser?

It references 247 directly, so we can decrease the value in the Priority Queue without having to *find* 247 first in the Priority Queue.

This avoids a search for 247, which might require looking at every entry, taking O(n) time for a Priority Queue of n elements.



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As it does, the Decreaser continues to follow it, no matter where it goes.

The data structure returns an entry's unique Decreaser object as the result of insertion.

This provides a fast method for decreasing the value, as shown on the next slides.


























Applications

• Scheduling Tasks with Priorities

- Find/Handle highest-priority task first
- E.g. in computer operating systems

• Searching for the Best Solution

- Add solutions to PQ as they are found
- At any time, can query/remove the optimum
- Cost of solutions may decrease over time
- (e.g. shortest path to each node in a graph)



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- Add solutions to PQ as they are found
- At any time, can query/remove the optimum
- Cost of solutions may decrease over time
- (e.g. shortest path to each node in a graph)
- Can you think of others?



Performance Goals for Priority Queue

- Let *n* be the size of the queue at a given time.
- peekMin() should be constant-time
- Want "nice" complexity for insert, decrease, extractMin as fcn of n.
- Ideally, all these operations should take time sub-linear in n (i.e. o(n))

Ideas? (Analyzed in Studio 3)

• Unsorted linked list?

PQ ops needed: insert(v) o(n) decrease(item, k) extractMin() O(1) peekMin()

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 - [just as bad as unsorted list]

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PQ ops needed: insert(v) o(n)-{decrease(item, k) extractMin() O(1) peekMin()

Argh – we need a new data structure to meet better-than-Θ(n) performance goals for both insertion and extraction!

A Brief Diversion: Trees

• Lists are a one-dimensional data structure

- One-dimensional connections (forward, back)
- We can use them to implement other data structures
 - Queue
 - Stack

• We now consider trees

- These are two-dimensional
- Movement up or down
- Movement left or right

• We will use trees to implement several interesting data structures

- Many definitions
- Here's an example:



Text p. 1088 (Appendix B)

- Many definitions
- Here's an example
- Some notes:
 - Trees have
 - Nodes



- Many definitions
- Here's an example
- Some notes:
 - Trees have
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 - Edges



- Many definitions
- Here's an example
- Some notes:
 - Trees have
 - Nodes
 - Edges
 - The edges are undirected



- Many definitions
- Here's an example
- Some notes:
 - Tree is upside down!





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- Many definitions
- Here's an example
- Some notes:
 - Tree is upside down!
 - We speak of a parent



- Many definitions
- Here's an example
- Some notes:
 - Tree is upside down!
 - We speak of a parent
 - And its children
 - They are siblings



- Many definitions
- Here's an example
- Some notes:
 - Tree is upside down!
 - We speak of a parent
 And its children
 - For now
 - A tree is rooted
 - Root is orphan node



- Each node occurs at some *depth* from the root
 - The root is at depth 0



 Each node occurs at some *depth* from the root

 The root is at depth0

 The height of a tree is the maximum depth among all of the tree's nodes



- Each node occurs at some *depth* from the root

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 The height of a tree is the maximum depth among all of the tree's
 - nodes
- Some nodes are *leaves*



- Each node occurs at some *depth* from the root

 The root is at depth 0

 The height of a tree is the maximum depth
 - the maximum depth among all of the tree's nodes
- Some nodes are *leaves*
- Others are
 internal nodes



 If the left-to-right orientation of the children matters, tree is ordered



- If the left-to-right orientation of the children matters, tree is ordered
- The *degree* of a node is the count of its children


OK, Back to Priority Queues...

Specializing Trees for Our Needs

• We'll focus on binary trees – every node has at most two children.

• We'll focus on compact binary trees – nodes are always added top-to-bottom and left-to-right

Specializing Trees for Our Needs

- We'll focus on binary trees every node has at most two children.
- We'll focus on compact binary trees nodes are always added top-to-bottom and left-to-right
- (There is a unique compact binary tree with n nodes)



























A **binary heap** is a compact binary tree with an ordering invariant – the heap property.

Heap property: a special relationship between each parent and its children



p.value ≤ min(a.value, b.value)

property for *min-first* heaps!

• Says *nothing* about how a.value and b.value compare

Examples

• Has heap property



Examples

• Has heap property



• Lacks heap property (what do you see that is wrong?)



Examples

• Has heap property



• Lacks heap property



Heap Property Implies Fast peekMin()

- In a heap, the heap property applies between every node and its children (if any).
- So where is the smallest element in a binary heap?

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Heap Property Implies Fast peekMin()

- In a heap, the heap property applies between every node and its children (if any).
- So where is the smallest element in a binary heap?
- At the root, of course?
- Better prove it...

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 - so p contains value p, a_1 contains value a_1 , and so on
 - Consider the sequence of proper ancestors of p
 - $\bullet \quad a_1 a_2 \dots a_n$



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 - **a**₁ $a_2 \dots a_n$
 - Applying the **heap property** we obtain:

$$a_n \leq \ldots \leq a_1 \leq p$$

а

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• This contradicts the claim that a_n is not a minimal element $Q \in D$

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Binary Heap Operations

- How do we implement
 - insert
 - extractMin
 - decrease
Binary Heap Operations

- How do we implement
 - insert
 - extractMin

decrease
We'll do this one first

87 91 31 17 46 77 79 4 58







































• Claim: if you can do decrease(), you can do insert()!

Algorithm for insert?







• Claim: if you can do decrease(), you can do insert()!



• Will argue that insert() reduces to decrease()



- Will argue that insert() reduces to decrease()
- ["If you can do decrease, here's how to use it for insert"] 135













Consider the following values in a heap 4 The empty nodes are not really there yet in this heap • But we could regard them as having infinite value Upon insertion value decreases from ∞ to inserted element's value 0 But we know how to handle this already So insert is reduced to decrease 0 17 46 87 79 31 ∞ ∞ ∞ 91 12 decrease(12)


















One More Operation

- extractMin remove smallest element of heap
- We know where the smallest element is... [root]

• But once we remove it, tree is no longer compact!











Wait, what?????

- The tree is compact again hooray!
- But *heap property* at root may now be violated boo!

- How can we we fix up the tree to be a heap again?
- Will use another swapping procedure: heapify




















































Pause... you try it

Take a minute to work through the next couple of extractions yourself...
































































































Time For Performance Analysis

• We now have **correct** procedures for the binary heap operations

Time For Performance Analysis

- We now have **correct?** procedures for the binary heap operations
- (Should really write proofs that heap property is restored... later)
- Right now, we ask: just how fast are these operations?

Intuition

• We want to give the cost of operations on a heap of size *n*.

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- An insert or decrease might move a value from the bottom of the tree up to the root.
- An extractMin might move a value (the new root) from the root of the tree down to the bottom.
- So we need to reason about how tall a heap with n elements is.











Theorem

• A complete binary tree (all non-leaves have two children) of height k has 2^{k+1}-1 nodes.

• Lemma: a complete binary tree of height k has 2^k leaves.

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- **Base**: $k = 0 \rightarrow tree$ is a single node $\rightarrow 2^0 = 1$ leaf.
- Ind: Suppose true for tree T of height k.
- We extend T by one level, adding two leaves below each node at the bottom of T. By IH, T has 2^k leaves, so extension has 2^{k+1}.

Back To Theorem...

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- Ind: Suppose true for tree T of height k.
- By IH, T has 2^{k+1} 1 nodes. Adding k+1st level adds 2^{k+1} leaves.

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by Lemma

- By IH, T has 2^{k+1} 1 nodes. Adding k+1st level adds 2^{k+1} leaves.
- Extended tree has $2(2^{k+1}) 1 = 2^{k+2} 1$ nodes. QED

So What?

- Complete binary tree of height k has Θ(2^k) nodes.
- Hence, complete binary tree with n nodes has height Θ(log n).

So What?

- Complete binary tree of height k has $\Theta(2^k)$ nodes.
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- What about compact but not complete trees?

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- Complete binary tree of height k has $\Theta(2^k)$ nodes.
- Hence, complete binary tree with n nodes has height $\Theta(\log n)$.
- What about compact but not complete trees?
- All levels except the bottom are full → can show tree of height k has at least 2^k nodes.
- Conclude that a **compact** tree with n nodes still has height $\Theta(\log n)$.

Conclusions About Running Time

- decrease/insert/heapify may move an element from the bottom to top or top to bottom of a compact tree $-\Theta(\log n)$ levels.
- Time to move is O(1) per level of tree.
- Conclude that these operations take *worst-case* time $\Theta(\log n)$.

Another Way to Analyze Complexity

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swap values of nodes v and c
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Another Way to Analyze Complexity

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Heapify(tree rooted at c)

• How can we analyze complexity of code like this?

Basic Approach

- Suppose a recursive procedure runs in time T(n) on inputs of size n.
- Procedure does work f(n), plus a recursive call on input of size g(n) < n.
- Then we can write T(n) = T(g(n)) + f(n)

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Let's apply this approach to the analysis of heapify













































Let's compute the ratio


the shaded tree
$$2^{h-1+1}-1=2^h-1$$

#nodes in this tree:

$$2^{h+1} - 1 - 2^{h-1}$$

$$\frac{2^h - 1}{2^{h+1} - 2^{h-1} - 1}$$

6

the shaded tree
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#nodes in this tree:

$$2^{h+1} - 1 - 2^{h-1}$$

$$= \frac{2^{h} - 1}{2^{h+1} - 2^{h-1} - 1}$$
$$= \frac{2 \times 2^{h-1} - 1}{4 \times 2^{h-1} - 2^{h-1} - 1}$$

the shaded tree
$$2^{h-1+1}-1=2^h-1$$

#nodes in this tree:

$$2^{h+1} - 1 - 2^{h-1}$$

$$= \frac{2^{h} - 1}{2^{h+1} - 2^{h-1} - 1}$$

= $\frac{2 \times 2^{h-1} - 1}{4 \times 2^{h-1} - 2^{h-1} - 1} = \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1}$

Let's compute the ratio $2^{h-1+1} - 1 = 2^h - 1$ #nodes in $2 \times 2^{h-1} - 1$ shaded tree $3 \times 2^{h-1} - 1$ $2^{h+1} - 1 - 2^{h-1}$ #nodes in this tree: $2^{h} - 1$ $2^{h+1} - 2^{h-1} - 1$ $2 \times 2^{h-1} - 1$ $2 \times 2^{h-1} - 1$ $4 \times 2^{h-1} - 2^{h-1} - 1$ $3 \times 2^{h-1} - 1_{200}$

$\begin{array}{c} \text{Let's compute the ratio} \\ & \stackrel{\text{\#nodes in}}{\text{shaded tree}} \ 2^{h-1+1}-1 = 2^h-1 \\ & \stackrel{\text{\#nodes in this tree:}}{2^{h+1}-1-2^{h-1}} \end{array} = \frac{2 \times 2^{h-1}-1}{3 \times 2^{h-1}-1} \end{array}$

$$\begin{array}{c|c} \mbox{#nodes in} & 2^{h-1+1}-1 = 2^h-1 \\ \hline \mbox{shaded tree} & 2^{h-1}-1 = 2^{h-1} \end{array} = \frac{2 \times 2^{h-1}-1}{3 \times 2^{h-1}-1} \end{array}$$

$$\lim_{h \to \infty} \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1}$$

$$\begin{array}{c|c} \begin{array}{c} \text{\#nodes in} \\ \text{shaded tree} \end{array} 2^{h-1+1} - 1 = 2^h - 1 \\ \end{array} = \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1} \end{array} \\ \end{array}$$

$$\lim_{h \to \infty} \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1}$$

$$\frac{\substack{\text{#nodes in shaded tree}}}{2^{h-1+1}-1=2^h-1} = \frac{2\times 2^{h-1}-1}{3\times 2^{h-1}-1}$$

$$\lim_{h \to \infty} \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1} = \frac{2}{3}$$

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$$\lim_{h \to \infty} \frac{2 \times 2^{h-1} - 1}{3 \times 2^{h-1} - 1} = \frac{2}{3}$$

2

 $=\frac{1}{3}$

#nodes in shaded tree

#nodes in the larger tree









• T(n) =

- k constant time spent on the top 3 nodes
- + T(2n/3)
- T(n) = T(2n/3) + k

• T(n) =

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- k constant time spent on the top 3 nodes
- + T(2n/3)
- T(n) = T(2n/3) + k

If the size of our problem is multiplied by 1.5, to get T(150), it takes just one more step, so T(150) = 11 k

T(100) = T(66)	+ k
= T(44)	+ k + k
= T(29)	+ k + k + k
= T(19)	+ k + k + k + k
= T(12)	+ k + k + k + k + k
= T(8)	+ k + k + k + k + k + k
= T(5)	+ k + k + k + k + k + k
=T(3)	+ k + k + k + k + k + k + k
= T(2)	+ k + k + k + k + k + k + k + k
= T(1)	+ k + k + k + k + k + k + k + k + k
= 0	+ k + k + k + k + k + k + k + k + k + k

We will be able to show soon that this $T(n) = \Theta(\log n)$

- k constant time spent on the top 3 nodes
- + T(2n/3)

• T(n) =

• T(n) = T(2n/3) + k

If the size of our problem is multiplied by 1.5, to get T(150), it takes just one more step, so T(150) = 11 k

T(100)) = T(66)	+ k	
1	= T(44)	+ k + k	
	= T(29)	+ k + k + k	
	= T(19)	+ k + k + k + k	
	= T(12)	+ k + k + k + k + k	
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• T(n) =

- k constant time spent on the top 3 nodes
- + T(2n/3)
- T(n) = T(2n/3) + k
- [magic we have not yet studied but will do so next week]
- $T(n) = \Theta(\log n)$
- Same asymptotic result as we got the other way
- Approach applies to many recursive procedures, as we'll see

Summary of Binary Heap Performance

- Decrease: worst-case Θ(log n)
- Insert: worst-case Θ(log n) [reduction from decrease]
- ExtractMin: worst-case Θ(log n)

Summary of Binary Heap Performance

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Moral: we can dynamically maintain the minimum of a binary heap in time $\Theta(\log n)$ per operation.

• What does it cost to do n successive insertions into an empty heap?

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- So building a heap takes worst-case time O(n log n)
- (But in fact, this O is not a Θ see text for better bound!)

Practical advice: do not actually store your binary heap as a tree!

Efficient representation of binary heap

• Binary heaps have so far been depicted as trees

- And we could implement them that way
- But there is a more efficient treatment
- Motivated by
 - Max size is known a priori
 - Elements are always added to the end for insert (T thing)
 - In response to extractMin(), heapify() removes the last element

• So an array is actually a good way to store a tree

- But how do we keep track of
 - parents
 - children
- Easy solution to that for a binary tree

- An important implementation note
 - Java arrays
 - Start at 0

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 - Sonew int[10]



- An important implementation note
 - Java arrays
 - Start at 0
 - So new int[10]
 - Provides for 10 integer locations
 - Numbered 0....9
- We could start filling in the array at 0
- But for the purposes of the binary heap we will start at 1
 - The text does it this way, so we'll be consistent with it.
 - The math that follows is *very slightly* easier starting with 1
 - Older programming languages started arrays at 1 (some, like Matlab, still do)



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- So we will store the tree in an array
- It's a binary tree
 - So each node has at most 2 children
- It's compact
 - So it's predictable where childless parents will appear
 - Near the end



- So we will store the tree in an array
- How do we infer the relationship
 - Between a parent and its children
 - Between a child and its parent



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• If p is stored at index i

- The left child is stored at 2 x i
- The right child is stored at 2 x i + 1
- For every node n except the root
 - The parent of n is at $\left|\frac{n}{2}\right|$





- So we will store the tree in an array
- How do we infer the relationship
 - Between a parent and its children
 - Between a child and its parent
- The root will always be stored at 1
- Given a parent node p
 - Left child a
 - Right child b
- If p is stored at index i
 - The left child is stored at 2 x i
 - The right child is stored at 2 x i + 1
- For every node n except the root
 - The parent of n is at $\left|\frac{r}{r}\right|$





Back to our example, but using an array























Lab 3: Implement Heap

For studio

Some possible implementations

• Let's think through some implementation possibilities

- Using data structures we already know
- Reasoning about their complexity
- The "n" here
 - Means the current size of our priority queue

• Given a priority queue of n items

- How expensive is each of the methods we have described so far
- For a particular implementation
 - Binary heap
 - List
 - Links vs. array
 - Ordered vs. not ordered

Running example

Implementation	insert	extractMin
Unordered list		
Ordered list		
Unordered array		
Ordered array		

- Table will track complexity
- We are interested in *worst-case* times
 - We'll come back to this shortly

Running example

PQ contains 53, 92, 46

	\square	
Implementation	insert	extractMin
Unordered list		
Ordered list		
Unordered array		
Ordered array		











 \bigcup

insert

Θ(1)

extractMin































		\square	
	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
\Rightarrow	Ordered list		
	Unordered array		
	Ordered array		





	\square	
Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
\$ Ordered list		
Unordered array		
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- Many of us confuse
 - Bestvs. worst case

$$\circ$$
 $\Omega(\cdots)$ vs. $O(\cdots)$

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- Bestvs. worst case
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- To avoid this
 - First think about the function f(n) that characterizes the property of interest
 - Worst-case
 - Best-case
 - Average-case

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- Bestvs. worst case
- \circ $\Omega(\cdots)$ vs. $O(\cdots)$
- To avoid this
 - First think about the function f(n) that characterizes the property of interest
 - Worst-case
 - Best-case
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 - Then think about whether that f(n) is bounded

• Many of us confuse

• Bestvs. worst case

$$\circ$$
 $\Omega(\cdots)$ vs. $O(\cdots)$

- To avoid this
 - First think about the function f(n) that characterizes the property of interest
 - Worst-case
 - Best-case
 - Average-case
 - Then think about whether that f(n) is bounded
 - From above $O(\cdots)$

Many of us confuse

Bestvs, worst case 0

$$\circ$$
 $\Omega(\cdots)$ vs. $O(\cdots)$

- To avoid this
 - First think about the function f(n) that characterizes the property of interest Ο
 - Worst-case
 - **Best-case**
 - Average-case
 - Then think about whether that f(n) is bounded Ο

 - From above $O(\cdots)$ From below $\Omega(\cdots)$

Many of us confuse

Bestvs, worst case 0

$$\circ$$
 $\Omega(\cdots)$ vs. $O(\cdots)$

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 - First think about the function f(n) that characterizes the property of interest Ο
 - Worst-case
 - **Best-case**
 - Average-case
 - Then think about whether that f(n) is bounded Ο
 - From above $O(\cdots)$ From below $\Omega(\cdots)$ Both $\Theta(\cdots)$

 - Both































What about arrays?

	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
	Ordered list	Θ(n)	Θ(1)
\Rightarrow	Unordered array		
	Ordered array		



PQ contains 53, 92, 46

	Implementation	insert	extractMin
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	Ordered array		



PQ contains 53, 92, 46

insert(84)

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
Ordered list	Θ(n)	Θ(1)
Unordered array		
Ordered array		



PQ contains 53, 92, 46

insert(84)

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
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Unordered array		
Ordered array		



PQ contains 53, 92, 46

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	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
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PQ contains 53, 92, 46

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Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
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Unordered array	Θ(1)	
Ordered array		



PQ contains 53, 92, 46

extractMin()

		V
Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
Ordered list	Θ(n)	Θ(1)
Unordered array	Θ(1)	
Ordered array		

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PQ contains 53, 92, 46

extractMin()

		V
Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
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Ordered array		

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PQ contains 53, 92, 46

extractMin() 53

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
Ordered list	Θ(n)	Θ(1)
Unordered array	Θ(1)	
Ordered array		



PQ contains 53, 92, 46

extractMin() 53

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
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Ordered array		



PQ contains 53, 92, 46

extractMin() 46

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
Ordered list	Θ(n)	Θ(1)
Unordered array	Θ(1)	
Ordered array		



PQ contains 53, 92, 46

extractMin() 46

Implementation	insert	extractMin
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\square	Ordered array		



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Unordered array	Θ(1)	Θ(n)		
Ordered array				

1. Find where 84 should go




PQ contains 53, 92, 46

insert(84)

1. Find where 84 should go

















Running example

PQ contains 53, 92, 46

insert(84)

	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
	Ordered list	Θ(n)	Θ(1)
	Unordered array	Θ(1)	Θ(n)
\Rightarrow	Ordered array		





46

53

92

 \int

 $\Theta(1)$

 $\Theta(n)$

Θ(1)

extractMin

 $\Theta(n)$

Θ(1)

 $\Theta(n)$



PQ contains 53, 92, 46

insert(84)

1. Find where 84 should go















One method for searching a phone book efficiently

• Look in the middle

- Is the target of your search later or earlier than what you find?
- Throw away the half of the phone book that cannot contain your target
 - Really, throw it away, or shred it, or burn it
- Repeat this procedure (recursively!) on the half you did not throw away
- We will soon study a general method to reason about this procedure's complexity
- But do you see what it is?
 - Think about the size of what remains to be searched
 - When it reaches 1 you are done
- $8 \rightarrow 4 \rightarrow 2 \rightarrow 1$ 3 steps $log_2 8$

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- Because these logarithms are so common, we abbreviate them using "Ig"

However, asymptotically the base doesn't matter, so we write O(log(n))





















Running example

PQ contains 53, 92, 46

			×
	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
	Ordered list	Θ(n)	Θ(1)
	Unordered array	Θ(1)	Θ(n)
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Running example

PQ contains 53, 92, 46

extractMin()

			×
	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
	Ordered list	Θ(n)	Θ(1)
	Unordered array	Θ(1)	Θ(n)
\Rightarrow	Ordered array	Θ(n)	

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Running example

Do you see how to modify Ordered array so that extractMin() can be done in constant time?

	Implementation	insert	extractMin
	Unordered list	Θ(1)	Θ(n)
	Ordered list	Θ(n)	Θ(1)
	Unordered array	Θ(1)	Θ(n)
\Rightarrow	Ordered array	Θ(n)	Θ(n)

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Running example

• Not so great

- o Lists
- Arrays

• Much better

- Use a heap
- A kind of a tree
- Implemented using an array
- \circ Provides O(log(n)) time bound on all operations
 - O(1) peek at minimum element

Implementation	insert	extractMin
Unordered list	Θ(1)	Θ(n)
Ordered list	Θ(n)	Θ(1)
Unordered array	Θ(1)	Θ(n)
Ordered array	Θ(n)	Θ(n)

Enrichment

https://xkcd.com/835/

• Don't forget to read the mouseover text